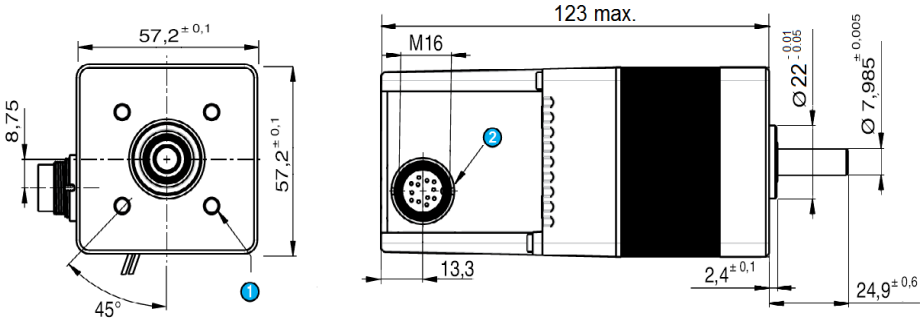
DCmind Brushless motor
Data sheet 80 140 079

Series
80 140 TNI21



1 4 x M5 trheaded holes on 40mm diameter, 4,5 mm thread depth

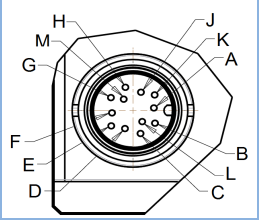
2 M16 male connector - 12 contacts

General characteristics

Power supply		
Direct current voltage supply		✓
Nominal voltage range	Vdc	12 -> 32
Max. current	A	10

Motor characteristics (1)		12 Vdc	24 Vdc	32 Vdc	
At no load					
Max. output speed	rpm	2 900	4 000	4 000	
Current at the max output speed	A	0,34	0,29	0,27	
Standby current	A	0,08	0,09	0,09	+-10%
At nominal					
Speed	rpm	1 900	4 000	4 000	+-10%
Torque (2)	mNm	193	184	178	
Output power	W	38	77	75	+-10%
Current	A	5,2	4,4	3,2	
Efficiency	%	62	74	73	
At max. output power					
Speed	rpm	1 600	3 050	4 000	
Torque	mNm	250	358	358	
Output power	W	42	114	150	+-10%
Current	A	6,5	10	10	
Efficiency	%	53	48	47	
At peak torque					
Speed	rpm	930	3 050	4 000	
Torque	mNm	358	358	358	
Output power	W	35	114	150	
Current	A	10	10	10	+-10%
Others					
Life (3)	h	20 000			
Rotor inertia	gcm²	75			
Thermal Resistance	°/W	3			
Thermal time constant	mn	20			
Rotor pole number		4			
Cogging torque	mNm	11			
Weight	kg	0,95			
Noise level	dBA	40			

Connecting		
M16 male connector - 12 contacts		Lumberg 0315 12
+ 12Vdc -> + 32 Vdc	E + F	
0V	G + M	
0V	H	
Input: ON/OFF	C	
Input: Direction	B	
Input: Speed	J	
Input: Torque limit	D	
Output: Pulse	A	
Output: Torque limit reached	K	
Output: Direction	L	



Accessory			
2 meters shielded cable with M16 female connector - 12 pins			
Part number	**15 275 008**	Cable with 12 wires AWG24	
Note: G and M wires have to be connected together. E and F wires have to be connected together			
A = white	B = brown	C = green	D = yellow
E = grey	F = pink	G = blue	H = red
J = black	K = purple	L = grey/pink	M = red/blue

Drive		
Type	**TNI21**	
Built-in drive	✓	
Internal encoder	12 pulses per turn	
Control		
Speed	PWM	
Torque	PWM	
4 quadrants - low braking	✓	
4 quadrants with regenerative energy		
Type" Trapezoidal"	✓	
Security		
Short-circuit of outputs	✓	
Input inverted	✓	
Low voltage	Vdc	< 10
Short high voltage	Vdc	> 36
Stop at max internal drive temperature (2)	°C	110
Drive temperature allowing to restart	°C	90

Generic parameters			
Output shaft with ball bearings		✓	
Max. Radial force (12mm from front face)		N	40
Max. axial force(4)		N	20
Temperature range	CEI60068-2-1/2	°C	-30 -> +70
Storage temperature		°C	-40 -> +80
Dielectric 1min 2mA 50Hz	CEI60335	Vdc	
Motor insulation	CEI60085	class	E
Salt spray	CEI60068-2-58	severity	48h
Degree of protection (output shaft not included)	CEI60529	IP	65M
EMC			
Electrostatic Discharge	CEI61000-4-2	level	3
Electrical fast transsient / burst test	CEI61000-4-4	level	3
Surge test	CEI61000-4-5	level	1
Radiated emission	EN55022	class	B
Approvals			
ROHS	2002/95/CE	✓	
EC		✓	

Notes
Values without tolerences are average production values.
Added informations are in "TNI21 manual and security" on www.crouzet.com
Motor not protected in case of reversed power voltage
(1) Cold motor, 20 ° C ambient temperature, full speed
(2) Max torque for continuous operation at 20 ° C, decrease this value for higher ambient temperature
(3) Continuously rated torque, zero radial and axial loads
(4) Pinion or pulley fitting are done at the Crouzet factory, before final assembly.

Specifications subject to change without notice. Updated july 8, 2013.

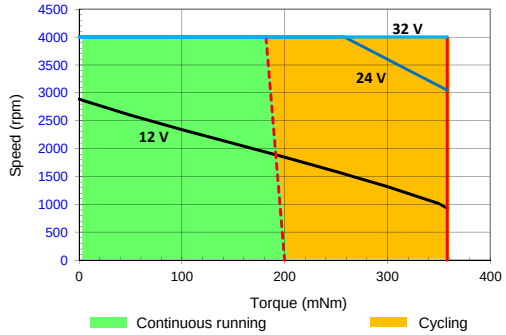
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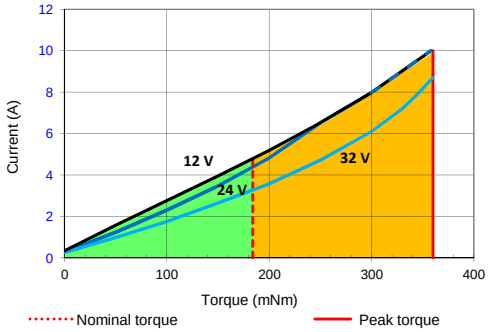
Drive electrical datas

Max. product characteristics				
Parameters				
Max. voltage supply "Vcc"	Vdc	39		
Max. current "Icc max"	A	12		
Max. voltage on inputs "Vin max"	Vdc	39		
Max. voltage on outputs "Vout max"	Vdc	39		
Max. output current "Iout max"	mA	50		
Running datas				
Parameters		Min	Typical	Max
Voltage suplly "Vcc"	Vdc	10	12/24/32	36
Current "Icc"	A	-	6	12
Standby power "Wo"	W	-	2	-
Speed setting	rpm	120	-	4 000
Torque setting	mNm	35	-	360
Holding torque setting	mNm	35	-	150

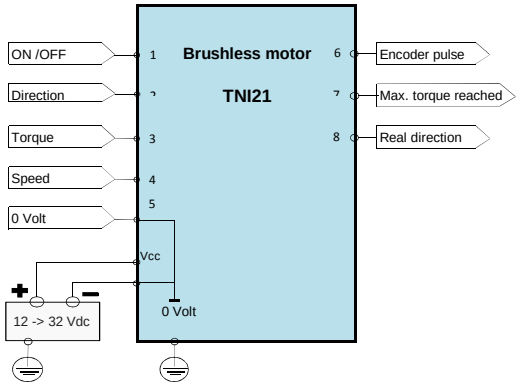
Input datas				
Parameters		Min	Typical	Max
Impedance - Input 1, 2	kΩ	-	57	-
Impedance - Input 3, 4	kΩ	-	69	-
Low level - Input 1, 2	Vdc	0	-	2
HIgh level - Input 1, 2	Vdc	4	-	39
Low level - Input 3, 4	Vdc	0	-	2
High level - Input 3, 4	Vdc	7,5	-	39
PWM frequency	Hz	100	-	2000
Output datas				
Parameters		Min	Typical	Max
Low level Outputs	Vdc	0	-	0,2
with "pull down resistor" = 4,7KΩ and Vcc = 24 V				
High level Outputs	Vdc	Vcc - 0,5	-	Vcc
with "pull down resistor" = 4,7KΩ and Vcc = 24 V				
= voltage supply added from eventual rejective voltage				

Speed-torque and current-torque curves





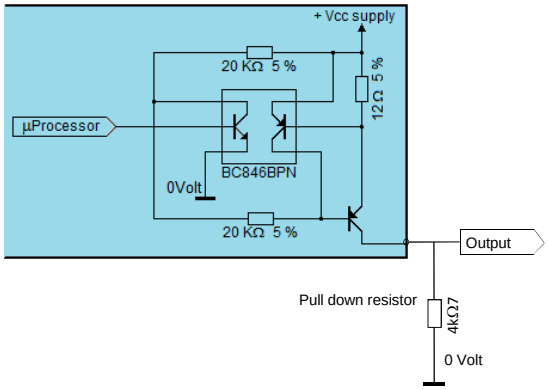
Wiring



Output equivalent circuit

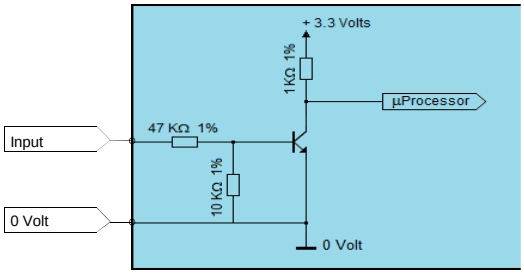
Outputs

PNP open collector output with internal current limitation (50mA)
Add a pull down resistor



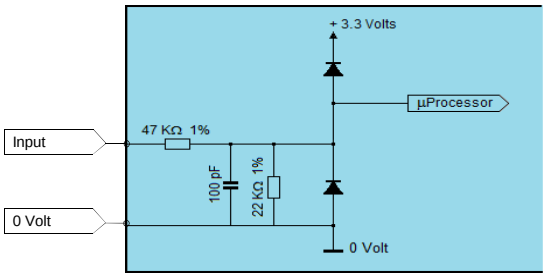
Inputs: ON/OFF and Direction

Inputs: ON/OFF and Direction



Inputs: Torque and Speed

Inputs: Torque and Speed



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